

### LM48520 Boomer® Audio Power Amplifier Series

# **Boosted Stereo Class D Audio Power Amplifier with Output Speaker Protection and Spread Spectrum**

### **General Description**

The LM48520 integrates a boost converter with a high efficiency Class D stereo audio power amplifier to provide up to 1W/ch continuous power into an  $8\Omega$  speaker when operating from 2.7V to 5.0V power supply with boost voltage (PV1) of 5.0V. The LM48520 utilizes a proprietary spread spectrum pulse width modulation technique that lowers RF interference and EMI levels. The Class D amplifier is a low noise, filterless PWM architecture that eliminates the output filter, reducing external component count, board area, power consumption, system cost, and simplifying design.

The LM48520 is designed for use in mobile phones and other portable communication devices. The high (78%) efficiency extends battery life when compared to Boosted Class AB amplifiers. The LM48520 features a low-power consumption shutdown mode. Shutdown may be enabled by driving the Shutdown pin to a logic low (GND). Also, external leakage is minimized via control of the ground reference via the SWOUT pin .

The LM48520 has 4 gain options which are pin selectable via Gain0 and Gain1 pins. Output short circuit prevents the device from damage during fault conditions. Superior click and pop suppression eliminates audible transients during power-up and shutdown.

### **Key Specifications**

Quiescent Power Supply Current11.5mA (typ)

■ Output Power  $(R_L = 8\Omega, THD+N \le 1\%, V_{DD} = 3.3V, PV1 = 5.0V)$ 

= 3.3V,PV1 = 5.0V) 1.1W (typ)

■ Shutdown Current 0.04µA (typ)

#### **Features**

- Click and Pop Suppression
- Low 0.04µA Shutdown Current
- 78% Efficiency
- Filterless Class D
- 2.7V 5.0V operation
- 4 Adjustable Gain settings
- Adjustable output swing limiter with Soft Clipping
- Speaker Protection
- Short circuit protection on Audio Amps
- Independent Boost and Amplifier shutdown pins

### **Applications**

- Mobile Phones
- PDAs
- Portable media
- Cameras
- Handheld games

### **Typical Application**

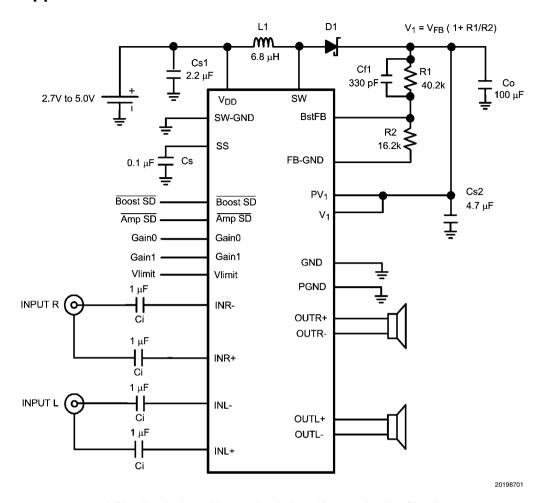
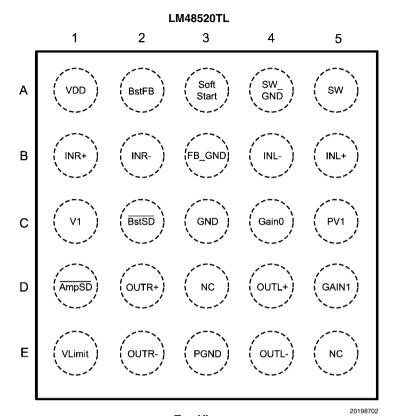


FIGURE 1. Typical LM48520 Audio Amplifier Application Circuit

### **Connection Diagrams**



Top View Order Number LM48520TL See NS Package Number TLA25AAA

Micro SMD Marking

XTG I5

Top View

X — Date Code

T — Die Traceability

G — Boomer Family

I5 — LM48520TL

# **Pin Descriptions**

| Pin Designator | Pin Name   | Pin Function  |  |
|----------------|------------|---|--|
| A1             | VDD        | Power Supply  |  |
| A2             | BstFB      | Regulator Feedback Input. Connect BstFB to an external resistive voltage divider to set the boost output voltage. |  |
| A3             | Soft Start | Soft start capacitor  |  |
| A4             | SW_GND     | Booster ground  |  |
| A5             | SW         | Drain of the Internal FET switch  |  |
| B1             | INR+       | Non-inverting right channel input   |  |
| B2             | INR-       | Inverting right channel input   |  |
| B3             | FB_GND     | Ground return for R1, R2 resistor divider   |  |
| B4             | INL-       | Inverting left channel input  |  |
| B5             | INL+       | Non-inverting left channel input  |  |
| C1             | V1         | Amplifier supply voltage. Connect to PV1.   |  |
| C2             | BstSD      | Regulator active low shutdown   |  |
| C3             | GND        | Ground  |  |
| C4             | Gain0      | Gain setting input 0  |  |
| C5             | PV1        | Amplifier H-bridge power supply. Connect to V1.   |  |
| D1             | AmpSD      | Amplifier active low shutdown   |  |
| D2             | OUTR+      | Non-inverting right channel output  |  |
| D3             | NC         | No connect  |  |
| D4             | OUTL+      | Non-inverting left channel output   |  |
| D5             | Gain1      | Gain setting input 1  |  |
| E1             | VLimit     | Set to control output clipping level  |  |
| E2             | OUTR-      | Inverting right channel output  |  |
| E3             | PGND       | Power ground  |  |
| E4             | OUTL-      | Inverting left channel output   |  |
| E5             | NC         | No connect  |  |

### **Absolute Maximum Ratings** (Note 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Thermal Resistance θ<sub>IA</sub> (TL)

40.5 °C/W

### **Operating Ratings**

Temperature Range

 $T_{MIN} \le T_A \le T_{MAX}$   $-40^{\circ}C \le T_A \le +85^{\circ}C$ Supply Voltage (V<sub>DD</sub>)  $2.7V \le V_{DD} \le 5.0V$ 

Amplifier Voltage (V1)

Not under Boosted Condition  $2.4V \le V_1 \le 5.5V$ 

Amplifier Voltage (PV1)

Under Boosted Condition  $3.0V \le PV_1 \le 5.0V$ 

### Electrical Characteristics V<sub>DD</sub> = 3.3V (Notes 1, 2)

The following specifications apply for  $V_{DD} = 3.3V$ ,  $A_V = 6dB$ ,  $R_L = 15\mu H + 8\Omega + 15\mu H$ ,  $f_{IN} = 1kHz$ , unless otherwise specified. Limits apply for  $T_A = 25^{\circ}C$ ,  $R_1 = 40.2k\Omega$ ,  $R_2 = 16.2k\Omega$ ,  $V_1 = PV_1 = 5V$ ,  $V_{limit} = GND$ . All electrical specifications are for amplifier and booster.

| Symbol            | Parameter                         | Conditions  | LM48520             |                       | Units         |
|-------------------|-----------------------------------|---|---------------------|-----------------------|---------------|
|                   |                                   |   | Typical<br>(Note 6) | Limit<br>(Notes 7, 8) | (Limits)      |
|                   |                                   | $V_{IN} = 0$ , $R_{LOAD} = \infty$  |                     |                       |               |
| I <sub>DD</sub>   |                                   | V <sub>DD</sub> = 2.7V  | 14.8                |                       |               |
|                   | Quiescent Power Supply Current    | $V_{DD} = 3.3V$   | 11.5                | 15.5                  | mA (max)      |
|                   |                                   | V <sub>DD</sub> = 5.0V  | 8.0                 |                       |               |
| SD                | Shutdown Current                  | V <sub>SHUTDOWN</sub> = GND   | 0.04                | 1.0                   | μΑ (max)      |
| / <sub>SDIH</sub> | Shutdown Voltage Input High       | For SD Boost, SD Amp  |                     | 1.4                   | V             |
| / <sub>SDIL</sub> | Shutdown Voltage Input Low        | For SD Boost, SD Amp  |                     | 0.4                   | V             |
| Γ <sub>wu</sub>   | Wake-up Time                      | Amplifier + Booster Wakeup  | 3                   |                       | ms            |
| / <sub>os</sub>   | Output Offset Voltage             |   | 5                   |                       | mV            |
| A <sub>V</sub>    | Gain                              | G0, G1 = GND<br>R <sub>L</sub> = ∞  | 6                   |                       | dB            |
|                   |                                   | $G0 = V_{DD}, G1 = GND$<br>$R_L = \infty$   | 12                  |                       | dB            |
|                   |                                   | $G0 = GND, G1 = V_{DD}$<br>$R_L = \infty$   | 18                  |                       | dB            |
|                   |                                   | G0, G1 = $V_{DD}$<br>$R_L = \infty$   | 24                  |                       | dB            |
| P <sub>o</sub>    |                                   | $R_L = 15\mu H + 8\Omega + 15\mu H$<br>THD+N = 1% (max),<br>f = 1kHz, 22kHz, BW<br>$V_{DD} = 3.3V$  | 1.1                 | 0.87                  | W (min)       |
|                   | Output Power                      | $R_L = 15\mu H + 8\Omega + 15\mu H$<br>THD+N = 10% (max),<br>f = 1kHz, 22kHz, BW<br>$V_{DD} = 3.3V$ | 1.3                 |                       | W             |
| ΓHD+N             | Total Harmonic Distortion + Noise | $P_{O} = 500$ mW, $f = 1$ kHz,<br>$R_{L} = 15\mu$ H + $8\Omega$ + $15\mu$ H,<br>$V_{DD} = 3.3$ V    | 0.04                |                       | %             |
| <sup>€</sup> OS   | Output Noise                      | V <sub>DD</sub> = 3.6V, f = 20Hz – 20kHz<br>Inputs to AC GND, A weighted                            | 32                  |                       | $\mu V_{RMS}$ |

| Symbol                   | Parameter  | Conditions  | LM48520             |                       | Units                  |
|--------------------------|--|---|---------------------|-----------------------|------------------------|
|                          |  |   | Typical<br>(Note 6) | Limit<br>(Notes 7, 8) | (Limits)               |
| PSRR                     | Power Supply Rejection Ratio                             | $V_{RIPPLE} = 200 \text{mV}_{P-P} \text{ Sine},$ $f_{RIPPLE} = 217 \text{Hz}$                 | 82                  |                       | dB                     |
|                          |  | $V_{RIPPLE} = 200 \text{mV}_{P-P} \text{ Sine},$ $f_{RIPPLE} = 1 \text{ kHz}$                 | 79                  |                       | dB                     |
| CMRR                     | Common Mode Rejection Ratio                              | $V_{RIPPLE} = 1V_{P-P}, f_{RIPPLE} = 217Hz$   | 67                  |                       | dB                     |
| η                        | Efficiency   | $P_{O} = 1W, f = 1kHz,$ $R_{L} = 15\mu H + 8\Omega + 15\mu H$ $V_{DD} = 3.3V$ $V_{DD} = 4.2V$ | 78                  |                       | %                      |
| $\overline{V_{FB}}$      | Feedback Pin Reference Voltage                           | (Note 11)   | 1.24                |                       | V                      |
| V <sub>out clipped</sub> | Output Voltage in clipped state with soft clip activated | $V_{limit} = 2V, R_L = 8\Omega, V_{IN} = 2V_P$<br>$V_{out clipped} = 8/3 (PV1 - 2V_{limit})$  | 2.5                 | 1.9<br>3.2            | Vpk (min)<br>Vpk (max) |

Note 1: All voltages are measured with respect to the GND pin, unless otherwise specified.

**Note 2:** Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

**Note 3:** The maximum power dissipation must be derated at elevated temperatures and is dictated by  $T_{JMAX}$ ,  $\theta_{JA}$ , and the ambient temperature,  $T_A$ . The maximum allowable power dissipation is  $P_{DMAX} = (T_{JMAX} - T_A) / \theta_{JA}$  or the given in Absolute Maximum Ratings, whichever is lower.

Note 4: Human body model, 100pF discharged through a 1.5k $\Omega$  resistor.

Note 5: Machine Model, 220pF-240pF discharged through all pins.

Note 6: Typicals are measured at 25°C and represent the parametric norm.

Note 7: Limits are guaranteed to National's AOQL (Average Outgoing Quality Level).

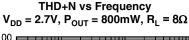
Note 8: Datasheet min/max specification limits are guaranteed by design, test, or statistical analysis.

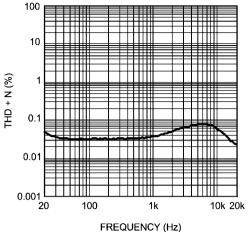
Note 9: Shutdown current is measured in a normal room environment. The Shutdown pin should be driven as close as possible to V<sub>in</sub> for minimum shutdown current.

Note 10: Shutdown current is measured with components R1 and R2 removed.

Note 11: Feedback pin reference voltage is measured with the Audio Amplifier disconnected from the Boost converter (the Boost converter is unloaded).

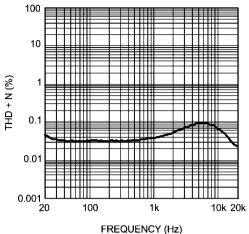
### **Typical Performance Characteristics**





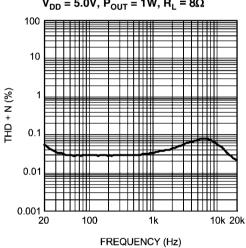
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### THD+N vs Frequency $V_{DD} = 3.3V, P_{OUT} = 900mW, R_{L} = 8\Omega$



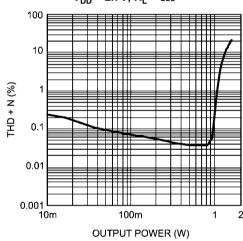
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THD+N vs Frequency  $V_{DD} = 5.0V$ ,  $P_{OUT} = 1W$ ,  $R_L = 8\Omega$ 



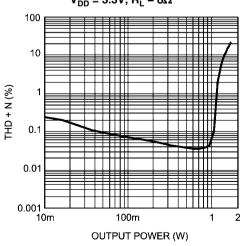
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THD+N vs Output Power  $V_{DD} = 2.7V, R_{L} = 8\Omega$ 



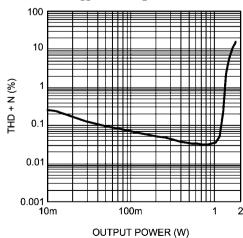
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#### THD+N vs Output Power $V_{DD} = 3.3V, R_{L} = 8\Omega$



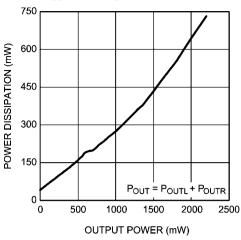
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#### THD+N vs Output Power $V_{DD} = 5.0V, R_{L} = 8\Omega$



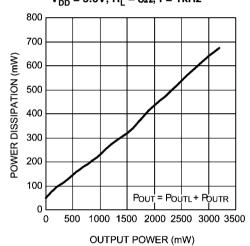
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# Power Dissipation vs Output Power $V_{DD}$ = 2.7V, $R_L$ = $8\Omega$ , f = 1kHz



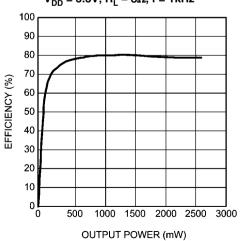
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# Power Dissipation vs Output Power $V_{DD} = 5.0V$ , $R_{L} = 8\Omega$ , f = 1 kHz



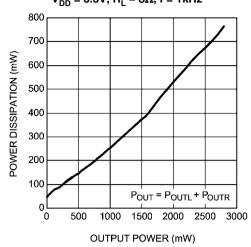
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# Efficiency vs Output Power $V_{DD} = 3.3V$ , $R_L = 8\Omega$ , f = 1kHz



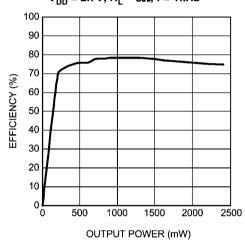
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# Power Dissipation vs Output Power $V_{DD} = 3.3V$ , $R_L = 8\Omega$ , f = 1kHz



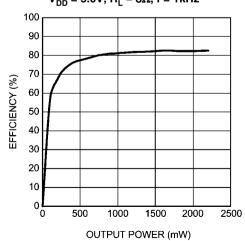
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# Efficiency vs Output Power $V_{DD} = 2.7V$ , $R_L = 8\Omega$ , f = 1kHz

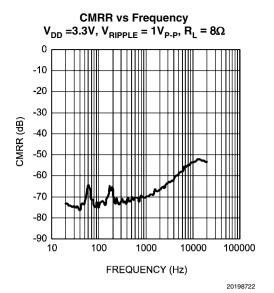


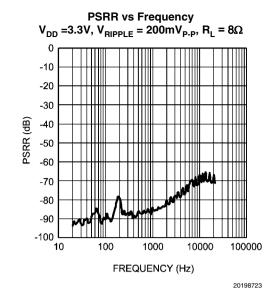
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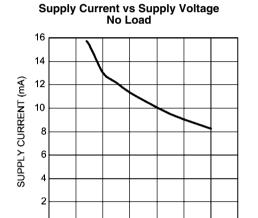
# Efficiency vs Output Power $V_{DD} = 5.0V$ , $R_L = 8\Omega$ , f = 1kHz

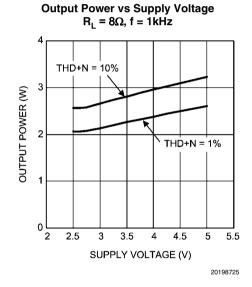


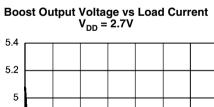
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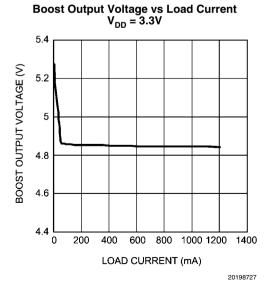
SUPPLY VOLTAGE (V)

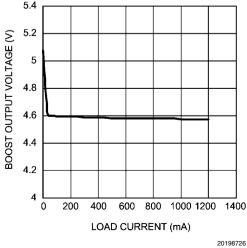
5 5.5

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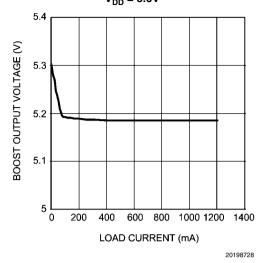
2.5

3 3.5





# Boost Output Voltage vs Load Current $V_{DD} = 5.0 V$



### **Application Information**

#### **GENERAL AMPLIFIER FUNCTION**

The LM48520 features a Class D audio power amplifier that utilizes a filterless modulation scheme, reducing external component count, conserving board space and reducing system cost. The outputs of the device transition from PV1 to GND with a 300kHz switching frequency. With no signal applied, the outputs ( $V_{LS+}$  and  $V_{LS-}$ ) switch with a 50% duty cycle, in phase, causing the two outputs to cancel. This cancellation results in no net voltage across the speaker, thus there is no current to the load in the idle state.

With the input signal applied, the duty cycle (pulse width) of the LM48520 outputs changes. For increasing output voltage, the duty cycle of  $V_{LS+}$  increases, while the duty cycle of  $V_{LS-}$  decreases. For decreasing output voltages, the converse occurs. The difference between the two pulse widths yields the differential output voltage.

#### **DIFFERENTIAL AMPLIFIER EXPLANATION**

The amplifier portion of the LM48520 is a fully differential amplifier that features differential input and output stages. A differential amplifier amplifies the difference between the two input signals. Traditional audio power amplifiers have typically offered only single-ended inputs resulting in a 6dB reduction in signal to noise ratio relative to differential inputs. The amplifier also offers the possibility of DC input coupling which eliminates the two external AC coupling, DC blocking capacitors. The amplifier can be used, however, as a single ended input amplifier while still retaining it's fully differential benefits. In fact, completely unrelated signals may be placed on the input pins. The amplifier portion of the LM48520 simply amplifies the difference between the signals. A major benefit of a differential amplifier is the improved common mode rejection ratio (CMRR) over single input amplifiers. The commonmode rejection characteristic of the differential amplifier reduces sensitivity to ground offset related noise injection, especially important in high noise applications.

#### **AMPLIFIER DISSIPATION AND EFFICIENCY**

The major benefit of a Class D amplifier is increased efficiency versus a Class AB. The efficiency of the LM48520 is attributed to the region of operation of the transistors in the output stage. The Class D output stage acts as current steering switches, consuming negligible amounts of power compared to their Class AB counterparts. Most of the power loss associated with the output stage is due to the IR loss of the MOSFET onresistance, along with switching losses due to gate charge.

#### **REGULATOR POWER DISSIPATION**

At higher duty cycles, the increased ON-time of the switch FET means the maximum output current will be determined by power dissipation within the LM48520 FET switch. The switch power dissipation from ON-time conduction is calculated by:

$$P_{D(SWITCH)} = DC x (I_{INDUCTOR(AVE)})^2 x R_{DS(ON)} (W)$$
 (1)

Where DC is the duty cycle.

#### SHUTDOWN FUNCTION

The LM48520 features independent amplifier and regulator shutdown controls, allowing each portion of the device to be disabled or enabled independently. AmpSD controls the

Class D amplifiers, while BstSD controls the regulator. Driving either inputs low disables the corresponding portion of the device, and reducing supply current.

When the regulator is disabled, both FB\_GND switches open, further reducing shutdown current by eliminating the current path to GND through the regulator feedback network. With the regulator disabled, there is still a current path from  $V_{DD}$ , through the inductor and diode, to the amplifier power supply. This allows the amplifier to operate even when the regulator is disabled. The voltage at PV1 and V1 will be:

$$V_{DD} - [V_D + (I_L \times DCR)]$$
 (2)

Where  $V_D$  is the forward voltage of the Schottky diode,  $I_L$  is the current through the inductor, and DCR is the DC resistance of the inductor. Additionally, when the regulator is disabled, an external voltage between 2.4V and 5.5V can be applied directly to PV1 and V1 to power the amplifier.

It is best to switch between ground and  $V_{DD}$  for minimum current consumption while in shutdown. The LM48520 may be disabled with shutdown voltages in between GND and  $V_{DD}$ , the idle current will be greater than the typical 0.1µA value. Increased THD+N may also be observed when a voltage of less than  $V_{DD}$  is applied to  $\overline{AmpSD}$ .

#### PROPER SELECTION OF EXTERNAL COMPONENTS

Proper selection of external components in applications using integrated power amplifiers, and switching DC-DC converters, is critical for optimizing device and system performance. Consideration to component values must be used to maximize overall system quality.

The best capacitors for use with the switching converter portion of the LM48520 are multi-layer ceramic capacitors. They have the lowest ESR (equivalent series resistance) and highest resonance frequency, which makes them optimum for high frequency switching converters.

When selecting a ceramic capacitor, only X5R and X7R dielectric types should be used. Other types such as Z5U and Y5F have such severe loss of capacitance due to effects of temperature variation and applied voltage, they may provide as little as 20% of rated capacitance in many typical applications. Always consult capacitor manufacturer's data curves before selecting a capacitor. High-quality ceramic capacitors can be obtained from Taiyo-Yuden, AVX, and Murata.

#### POWER SUPPLY BYPASSING FOR AMPLIFIER

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both PV1, V1 and  $V_{DD}$  pins should be as close to the device as possible.

#### **SELECTING INPUT CAPACITOR FOR AUDIO AMPLIFIER**

Input capacitors,  $C_{\rm IN}$ , in conjunction with the input impedance of the LM48520 forms a high pass filter that removes the DC bias from an incoming signal. The AC-coupling capacitor allows the amplifier to bias the signal to an optimal DC level. Assuming zero source impedance, the -3dB point of the high pass filter is given by:

$$f_{(-3dB)} = 1/2\pi R_{IN} C_{IN}$$
 (3)

Choose  $C_{\rm IN}$  such that  $f_{-3{\rm dB}}$  is well below that lowest frequency of interest. Setting  $f_{-3{\rm dB}}$  too high affects the low-frequency responses of the amplifier. Use capacitors with low voltage

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coefficient dielectrics, such as tantalum or aluminum electrolytic. Capacitors with high-voltage coefficients, such as ceramics, may result in increased distortion at low frequencies. Other factors to consider when designing the input filter include the constraints of the overall system. Although high fidelity audio requires a flat frequency response between 20Hz and 20kHz, portable devices such as cell phones may only concentrate on the frequency range of the frequency range of the spoken human voice (typically 300Hz to 4kHz). In addition, the physical size of the speakers used in such portable devices limits the low frequency response; in this case, frequencies below 150Hz may be filtered out.

# SELECTING OUTPUT CAPACITOR ( $\mathrm{C}_\mathrm{O}$ ) FOR BOOST CONVERTER

A single 100µF low ESR tantalum capacitor provides sufficient output capacitance for most applications. Higher capacitor values improve line regulation and transient response. Typical electrolytic capacitors are not suitable for switching converters that operate above 500kHz because of significant ringing and temperature rise due to self-heating from ripple current. An output capacitor with excessive ESR reduces phase margin and causes instability.

# SELECTING INPUT CAPACITOR (Cs1) FOR BOOST CONVERTER

An input capacitor is required to serve as an energy reservoir for the current which must flow into the coil each time the switch turns ON. This capacitor must have extremely low ESR, so ceramic is the best choice. We recommend a nominal value of 2.2µF, but larger values can be used. Since this capacitor reduces the amount of voltage ripple seen at the input pin, it also reduces the amount of EMI passed back along that line to other circuitry.

#### SELECTING SOFTSTART (C<sub>SS</sub>) CAPACITOR

The soft-start function charges the boost converter reference voltage slowly. This allows the output of the boost converter to ramp up slowly thus limiting the transient current at startup. Selecting a soft-start capacitor ( $C_{\rm SS}$ ) value presents a trade off between the wake-up time and the startup transient current. Using a larger capacitor value will increase wake-up time and decrease startup transient current while the apposite effect happens with a smaller capacitor value. A general guideline is to use a capacitor value 1000 times smaller than the output capacitance of the boost converter ( $C_{\rm O}$ ). A 0.1uF soft-start capacitor is recommended for a typical application.

# SETTING THE OUTPUT VOLTAGE ( $V_1$ ) OF BOOST CONVERTER

The output voltage is set using the external resistors R1 and R2 (see Figure 1). A value of approximately  $13.3 \mathrm{k}\Omega$  is recommended for R2 to establish a divider current of approximately  $92\mu\mathrm{A}$ . R1 is calculated using the formula:

$$R1 = R2 \times (V_1/1.23 - 1)$$
 (4)

# FEED-FORWARD COMPENSATION FOR BOOST CONVERTER

Although the LM48520's internal Boost converter is internally compensated, the external feed-forward capacitor  $C_{\rm f}$  is required for stability (see Figure 1). Adding this capacitor puts a zero in the loop response of the converter. The recommended frequency for the zero fz should be approximately 6kHz.  $C_{\rm f}1$  can be calculated using the formula:

$$C_f = 1 / (2 \times R1 \times fz)$$
 (5)

#### SELECTING DIODES FOR BOOST

The external diode used in Figure 1 should be a Schottky diode. A 20V diode such as the MBRS320T3 is recommended.

The MBRS320T3 series of diodes are designed to handle a maximum average current of 3A.

#### **DUTY CYCLE**

The maximum duty cycle of the boost converter determines the maximum boost ratio of output-to-input voltage that the converter can attain in continuous mode of operation. The duty cycle for a given boost application is defined as:

This applies for continuous mode operation.

#### SELECTING INDUCTOR VALUE

Inductor value involves trade-offs in performance. Larger inductors reduce inductor ripple current, which typically means less output voltage ripple (for a given size of output capacitor). Larger inductors also mean more load power can be delivered because the energy stored during each switching cycle is:

$$E = L/2 X (I_p)^2$$

Where "lp" is the peak inductor current. The LM48520 will limit its switch current based on peak current. With  $\rm I_{P}$  fixed, increasing L will increase the maximum amount of power available to the load. Conversely, using too little inductance may limit the amount of load current which can be drawn from the output. Best performance is usually obtained when the converter is operated in "continuous" mode at the load current range of interest, typically giving better load regulation and less output ripple. Continuous operation is defined as not allowing the inductor current to drop to zero during the cycle. Boost converters shift over to discontinuous operation if the load is reduced far enough, but a larger inductor stays continuous over a wider load current range.

During the TBDµs ON-time, the inductor current ramps up TBDA and ramps down an equal amount during the OFF-time. This is defined as the inductor "ripple current". It can also be seen that if the load current drops to about TBDmA, the inductor current will begin touching the zero axis which means it will be in discontinuous mode. A similar analysis can be performed on any boost converter, to make sure the ripple current is reasonable and continuous operation will be maintained at the typical load current values.

#### MAXIMUM SWITCH CURRENT

The maximum FET switch current available before the current limiter cuts in is dependent on duty cycle of the application. This is illustrated in a graph in the typical performance characterization section which shows typical values of switch current as a function of effective (actual) duty cycle.

# CALCULATING OUTPUT CURRENT OF BOOST CONVERTER (I<sub>AMP</sub>)

As shown in Figure 2 which depicts inductor current, the load current is related to the average inductor current by the relation:

$$I_{LOAD} = I_{IND}(AVG) \times (1 - DC)$$
 (6)

Where "DC" is the duty cycle of the application. The switch current can be found by:

$$I_{SW} = I_{IND}(AVG) + 1/2 (I_{RIPPLE})$$
 (7)

Inductor ripple current is dependent on inductance, duty cycle, input voltage and frequency:

$$I_{RIPPLE} = DC \times (V_{IN}-V_{SW}) / (f \times L)$$
 (8)

combining all terms, we can develop an expression which allows the maximum available load current to be calculated:

$$I_{LOAD}(max) = (1-DC)x(I_{SW}(max)-DC(V_{IN}-V_{SW}))/fL$$
 (9)

The equation shown to calculate maximum load current takes into account the losses in the inductor or turn-OFF switching losses of the FET and diode.

#### DESIGN PARAMETERS $V_{SW}$ AND $I_{SW}$

The value of the FET "ON" voltage (referred to as  $V_{\rm SW}$  in equations 4 thru 7) is dependent on load current. A good approximation can be obtained by multiplying the "ON Resistance" of the FET times the average inductor current.

FET on resistance increases at  $V_{\rm IN}$  values below 5V, since the internal N-FET has less gate voltage in this input voltage range (see Typical Performance Characteristics curves). Above  $V_{\rm IN}$  = 5V, the FET gate voltage is internally clamped to 5V

The maximum peak switch current the device can deliver is dependent on duty cycle. For higher duty cycles, see Typical Performance Characteristics curves.

#### **INDUCTOR SUPPLIERS**

The recommended inductor for the LM48520 is the NR8040T6R8N from Taiyo Yuden. When selecting an induc-

tor, make certain that the continuous current rating is high enough to avoid saturation at peak currents, where:

$$I_{IND} = (PV1 / V_{DD}) \times I_{LOAD(BOOST)}$$
 (10)

A suitable core type must be used to minimize core (switching) losses, and wire power losses must be considered when selecting the current rating.

### **PCB Layout Guidelines**

High frequency boost converters require very careful layout of components in order to get stable operation and low noise.

All components must be as close as possible to the LM48520 device. It is recommended that a four layer PCB be used so that internal ground planes are available.

Some additional guidelines to be observed (all designators are referencing Figure 1):

- 1. Keep the path between L1, D1, and Co extremely short. Parasitic trace inductance in series with D1 and Co will increase noise and ringing.
- 2. The feedback components R1, R2 and Cf1 must be kept close to the FB pin to prevent noise injection on the FB pin trace.
- 3. Since the external components of the boost converter are switching, L1 and D1 should be kept away from the input traces to prevent the noise from injecting into the input.
- 4. The power supply bypass capacitors, Cs1 and Cs2 should be placed as close to the LM48520 device as possible.

#### **GROUNDING GUIDELINES**

There are three grounds on the LM48520, GND, SW\_GND, and PGND. When laying out the PCB, it is critical to connect the grounds as close to the device as possible. The simplest way to do that is to place vias close to the GND, SW\_GND, and PGND bumps and connect the GND, SW\_GND, and PGND vias using a single ground plane in an inner layer of the PCB.

### **Output Speaker Protection Function**

The LM48520's output voltage limiter can be used to set a minimum and maximum output voltage swing magnitude. The voltage applied to the VLimit pin controls the limit on the output voltage level. The output level is determined by the following equation:

or

Where, Vout clipped = the desired output level measured in Vpk, PV1 = Boost output voltage, and Vlimit is the voltage applied the the Vlimit pin on the LM48520.

To disable the limiter, set Vlimit = 0V.

Figure 2 provides an example of how the output voltage limiter functions with V $_{DD}$  = 3.3V, A $_{V}$  = 6dB, PV1 = 5V, Vlimit = 2V, R $_{L}$  = 8 $\Omega$ , V $_{IN}$  = 2V $_{P}$ .

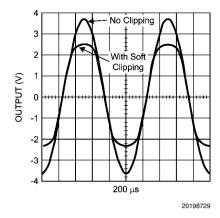
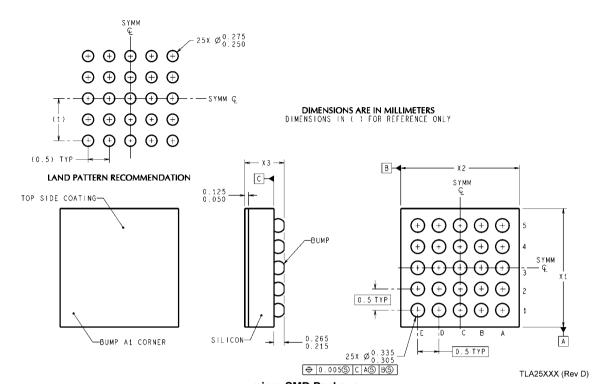


FIGURE 2. Soft Clipping vs No Clipping

# **Revision History**

| Rev  | Date     | Description                                   |  |
|------|----------|---|--|
| 1.0  | 02/27/08 | Initial release.                              |  |
| 1.01 | 03/07/08 | Added the Soft clipping vs No clipping curve. |  |
| 1.02 | 03/12/08 | Text edits.                                   |  |

### Physical Dimensions inches (millimeters) unless otherwise noted



micro SMD Package Order Number LM48520TL NS Package Number TLA25AAA X1 = 2.49mm, X2 = 2.49mm, X3 = 0.6mm,

### **Notes**

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